

# **Probability Distribution in the SABR Model of Stochastic Volatility**

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### **Abstract**

We study the SABR model of stochastic volatility [10]. This model is essentially an extension of the local volatility model [6], [4], in which a suitable volatility parameter is assumed to be stochastic. The SABR model admits a large variety of shapes of volatility smiles, and it performs remarkably well in the swaptions and caps / floors markets. We refine the results of [10] by constructing an accurate and efficient asymptotic form of the probability distribution of forwards. Furthermore, we discuss the impact of boundary conditions at zero forward on the volatility smile. Our analysis is based on a WKB type expansion for the heat kernel of a perturbed Laplace-Beltrami operator on a suitable hyperbolic Riemannian manifold.

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## 1 Introduction

The SABR model [10] of stochastic volatility attempts to capture the dynamics of smile in the interest rate derivatives markets which are dominated by caps / floors and swaptions. It provides a parsimonious, accurate, intuitive, and easy to implement framework for pricing, position management, and relative value in those markets. The model describes the dynamics of a single forward (swap or LIBOR) rate with stochastic volatility. The dynamics of the model is characterized by a function  $C(f)$  of the forward rate  $f$  which determines the general shape of the volatility skew, a parameter  $v$  which controls the level of the volatility of volatility, and a parameter  $\rho$  which governs the correlation between the changes in the underlying forward rate and its volatility. It is an extension of Black's model: choosing  $v = 0$  and  $C(f) = f$  reduces SABR to the lognormal Black model, while  $v = 0$  and  $C(f) = 1$  reduces it to the normal Black model.

The main reason why the SABR model has proven effective in the industrial setting is that, even though it is too complex to allow for a closed form solution, it has an accurate asymptotic solution. This solution, as well as its implications for pricing and risk management of interest derivatives, has been described in [10].

In this paper we further refine the results presented in [10]. Our developments go in two directions. First, we present a more systematic framework for generating an accurate, asymptotic form of the probability distribution in the SABR model. Secondly, we address the issue of low strikes, or the behavior of the model as the forward rate approaches zero.

Our way of thinking has been strongly influenced by the asymptotic techniques which go by the names of the *geometric optics* or the *WKB method*, and, most importantly, by the classical results of Varadhan [19], [20] (see also [18], [14] for more recent presentations and refinements). These techniques allow one to relate the short time asymptotics of the fundamental solution (or the *Green's function*) of Kolmogorov's equation to the differential geometry of the state space. From the probabilistic point of view, the Green's function represents the transition probability of the diffusion, and it thus carries all the information about the process.

Specifically, let  $\mathcal{U}$  denote the state space of an  $n$ -dimensional diffusion process with no drift, and let  $G_X(s, x)$ ,  $x, X \in \mathcal{U}$ , denote the Green's function. We also assume that the process is time homogeneous, meaning that the diffusion matrix is independent of  $s$ . Then, Varadhan's theorem states that

$$\lim_{s \rightarrow 0} s \log G_X(s, x) = -\frac{d(x, X)^2}{2}.$$

Here  $d(x, X)$  is the geodesic distance on  $\mathcal{U}$  with respect to a Riemannian metric which is determined by the coefficients of the Kolmogorov equation. This gives us the leading order behavior of the Green's function. To extract usable asymptotic information about the transition probability, more accurate analysis is necessary, but the choice of the Riemannian structure on  $\mathcal{U}$  dictated by Varadhan's theorem turns out to be key. Indeed, that Riemannian geometry becomes an important book keeping tool in carrying out the calculations, rather than merely fancy language. Technically speaking, we are led to studying the asymptotic properties of the perturbed Laplace - Beltrami operator on a Riemannian manifold.

In order to explain the results of this paper we define a universal function  $D(\zeta)$ :

$$D(\zeta) = \log \frac{\sqrt{\zeta^2 - 2\rho\zeta + 1} + \zeta - \rho}{1 - \rho},$$

where  $\zeta$  is the following combination of today's forward rate  $f$ , strike  $F$ , and a volatility parameter  $\sigma$  (which is calibrated so that the at the money options prices match the market prices):

$$\zeta = \frac{v}{\sigma} \int_F^f \frac{du}{C(u)}.$$

The function  $D(\zeta)$  represents a certain metric whose precise meaning is explained in the body of the paper. The key object from the point of view of option pricing is

the probability distribution of forwards  $P_F(\tau, f)$ . Our main result in this paper is the explicit asymptotic formula:

$$P_F(\tau, f) = \frac{\exp\left\{-D(\zeta)^2/2\tau v^2\right\}}{\sqrt{2\pi\tau}\sigma C(K)(\cosh D(\zeta) - \rho \sinh D(\zeta))^{3/2}} (1 + \dots).$$

In order not to burden the notation, we have written down the leading term only; the complete formula is stated in Section 5. To leading order, the probability distribution of forwards in the SABR model is Gaussian with the metric  $D(\zeta)$  replacing the usual distance.

From this probability distribution, we can deduce explicit expressions for implied volatility. The normal volatility is given by:

$$\sigma_n = \sigma C(F) \sqrt{\cosh D(\zeta) - \rho \sinh D(\zeta)} (1 + \dots).$$

Precise formulas, including the subleading terms and the impact of boundary conditions at zero forward, are stated in Section 5. To calculate the corresponding lognormal volatility one can use the results of [12].

We would like to mention that other stochastic volatility models have been extensively studied in the literature (notably among them the Heston model [13]). Useful presentations of these models are contained in [5] and [17]. We continue our approach to volatility modelling in [11].

A comment on our style of exposition in this paper. We chose to present the arguments in an informal manner. In order to make the presentation self-contained, we present all the details of calculations, and do not rely on general theorems of differential geometry, stochastic calculus, or the theory of partial differential equations. And while we believe that all the results of this paper could be stated and proved rigorously as theorems, little would be gained and clarity might easily get lost in the course of doing so.

The paper is organized as follows. In Section 2 we review the model and formulate the basic partial differential equation, the backward Kolmogorov equation. We also introduce the Green's and discuss various boundary conditions at zero. Section 3 is devoted to the description of the differential geometry underlying the SABR model. We show that the stochastic dynamics defining the model can be viewed as a perturbation of the Brownian motion on a deformed Poincare plane. The elliptic operator in the Kolmogorov equation turns out to be a perturbed Laplace-Beltrami operator. This differential geometric setup is key to our asymptotic analysis of the model which is carried through in Section 4. In Section 5 we derive the explicit formulas for the probability distribution and implied volatility which we have discussed above. In Appendix A we review the derivation of the fundamental solution of the heat equation on the Poincare plane. This solution is the starting point of our perturbation expansion. Finally, Appendix B contains some useful asymptotic expansions.

## 2 SABR model

In this section we describe the SABR model of stochastic volatility [10]. It is a two factor model with the dynamics given by a system of two stochastic differential equations. The state variables of the model can be thought of as the forward price of an asset, and a volatility parameter. In order to derive explicit expressions for the associated probability distribution and the implied volatility, we study the Green's function of the backward Kolmogorov operator.

### 2.1 Underlying process

We consider a European option on a forward asset expiring  $T$  years from today. The forward asset that we have in mind can be for instance a forward LIBOR rate, a forward swap rate, or the forward yield on a bond. The dynamics of the forward in the SABR model is given by:

$$\begin{aligned} dF_t &= \Sigma_t C(F_t) dW_t, \\ d\Sigma_t &= v \Sigma_t dZ_t. \end{aligned} \quad (1)$$

Here  $F_t$  is the forward rate process, and  $W_t$  and  $Z_t$  are Brownian motions with

$$\mathbf{E} [dW_t dZ_t] = \rho dt, \quad (2)$$

where the correlation  $\rho$  is assumed constant. We supplement the dynamics (1) with the initial condition

$$\begin{aligned} F_0 &= f, \\ \Sigma_0 &= \sigma. \end{aligned} \quad (3)$$

Note that we assume that a suitable numeraire has been chosen so that  $F_t$  is a martingale. The process  $\Sigma_t$  is the stochastic component of the volatility of  $F_t$ , and  $v$  is the volatility of  $\Sigma_t$  (the "volga") which is also assumed to be constant.

The function  $C(x)$  is defined for  $x > 0$ , and is assumed to be positive, smooth, and integrable around 0;

$$\int_0^K \frac{du}{C(u)} < \infty, \text{ for all } K > 0. \quad (4)$$

Two examples of  $b$ , which are particularly popular among financial practitioners, are functions of the form:

$$C(x) = x^\beta, \text{ where } 0 \leq \beta < 1 \quad (5)$$

(stochastic CEV model), or

$$C(x) = x + a, \text{ where } a > 0 \quad (6)$$

(stochastic shifted lognormal model).

Our analysis uses an asymptotic expansion in the parameter  $v^2 T$ , and we thus require that  $v^2 T$  be small. In practice, this is an excellent assumption for medium and

longer dated options. Typical for shorter dated options are significant, discontinuous movements in implied volatility. The SABR model should presumably be extended to include such jump behavior of short dated options.

The process  $\Sigma_t$  is purely lognormal and thus  $\Sigma_t > 0$  almost surely. Since, depending on the choice of  $C(x)$ ,  $F_t$  can reach zero with non-zero probability, we should carefully study the boundary behavior of the process (1), as  $F_t$  approaches 0. Later on in this paper we shall impose the Dirichlet and Neumann boundary conditions on the SABR dynamics. In the meantime, it will be convenient to work with free boundary conditions, which essentially consist in allowing  $F_t$  to take on arbitrary values. To this end, we extend the function  $C(x)$  to all values of  $x$  by setting

$$C(-x) = C(x), \text{ for } x < 0. \quad (7)$$

The so extended  $C(x)$  is an even function,  $C(-x) = C(x)$ , for all values of  $x$ , and thus the process (1) is invariant under the reflection  $F_t \rightarrow -F_t$ . The state space of the extended process is thus the upper half plane.

A special case of (1) which will play an important role in our analysis is the case of  $C(x) = 1$ , and  $\rho = 0$ . In this situation, the basic equations of motion have a particularly simple form:

$$\begin{aligned} dF_t &= \Sigma_t dW_t, \\ d\Sigma_t &= v\Sigma_t dZ_t, \end{aligned} \quad (8)$$

with  $\mathbf{E}[dW_t dZ_t] = 0$ . We shall refer to this model as the *normal SABR model*.

Local volatility [6], [4], is defined as the conditional expectation value

$$\sigma_K(T, f, \sigma)^2 dT = \mathbb{E} \left[ (dF_t)^2 \mid F(0) = f, F_t = K, \Sigma(0) = \sigma \right], \quad (9)$$

or, explicitly,

$$\sigma_K(T, f, \sigma)^2 = C(K)^2 \mathbb{E} \left[ (\Sigma_t)^2 \mid F(0) = f, F_t = K, \Sigma(0) = \sigma \right]. \quad (10)$$

## 2.2 Green's function

Green's functions arise in finance as the prices of Arrow-Debreu securities. We consider the Arrow-Debreu security whose payoff at time  $T$  is given by Dirac's delta function  $\delta(F_T - F, \sigma_T - \Sigma)$ . The time  $t < T$  price  $G = G_{T,F,\Sigma}(t, f, \sigma)$  of this security is the solution to the following parabolic partial differential equation:

$$\frac{\partial G}{\partial t} + \frac{1}{2} \sigma^2 \left( C(f)^2 \frac{\partial^2 G}{\partial f^2} + 2v\rho C(f) \frac{\partial^2 G}{\partial \sigma \partial f} + v^2 \frac{\partial^2 G}{\partial \sigma^2} \right) = 0, \quad (11)$$

with the terminal condition:

$$G_{T,F,\Sigma}(t, f, \sigma) = \delta(f - F, \sigma - \Sigma), \text{ at } t = T. \quad (12)$$

This equation should also be supplemented by a boundary condition at infinity such that  $G$  is financially meaningful. Since the payoff takes place only if the forward has a

predetermined value in a finite amount of time, the value of the Arrow-Debreu security has to tend to zero as  $F$  and  $\Sigma$  become large:

$$G_{T,F,\Sigma}(t, f, \sigma) \rightarrow 0, \quad \text{as } F, \Sigma \rightarrow \infty. \quad (13)$$

Thus  $G_{T,F,\Sigma}(t, f, \sigma)$  is a Green's function for (11). Once we have constructed it, we can price any European option. For example, the price  $C_{T,K}(t, f, \sigma)$  of a European call option struck at  $K$  and expiring at time  $T$  can be written in terms of  $G_{T,F,\Sigma}(t, f, \sigma)$  as

$$C_{T,K}(t, f, \sigma) = \int (F - K)^+ G_{T,F,\Sigma}(t, f, \sigma) dF d\Sigma, \quad (14)$$

where, as usual,  $(F - K)^+ = \max(F - K, 0)$ , and where the integration extends over the upper half plane  $\{(F, \Sigma) \in \mathbb{R}^2 : \Sigma > 0\}$ .

Note that the process (1) is time homogeneous, and thus  $G_{T,F,\Sigma}(t, f, \sigma)$  is a function of the time to expiry  $\tau = T - t$  only. Denoting

$$G_{F,\Sigma}(\tau, f, \sigma) \equiv G_{T,F,\Sigma}(t, f, \sigma),$$

and

$$C_K(\tau, f, \sigma) \equiv C_{T,K}(t, f, \sigma),$$

we can reformulate (11) - (12) as the initial value problem:

$$\frac{\partial G}{\partial \tau} = \frac{1}{2} \sigma^2 \left( C(f)^2 \frac{\partial^2 G}{\partial f^2} + 2v\rho C(f) \frac{\partial^2 G}{\partial f \partial \sigma} + v^2 \frac{\partial^2 G}{\partial \sigma^2} \right), \quad (15)$$

and

$$G_{F,\Sigma}(\tau, f, \sigma) = \delta(f - F, \sigma - \Sigma), \quad \text{at } \tau = 0. \quad (16)$$

Introducing the marginal probability distribution

$$P_F(\tau, f, \sigma) = \int_0^\infty G_{F,\Sigma}(\tau, f, \sigma) d\Sigma, \quad (17)$$

we can express the call price (14) as

$$C_K(\tau, f, \sigma) = \int_{-\infty}^\infty (F - K)^+ P_F(\tau, f, \sigma) dF. \quad (18)$$

This formula has the familiar structure, and one of our main goals will be to derive a useful expression for  $P_F(\tau, f)$ .

It is also easy to express the local volatility in terms of the Green's function. Indeed,

$$\sigma_K(\tau, f, \sigma)^2 = \frac{C(K)^2 \int_0^\infty \Sigma^2 G_{K,\Sigma}(\tau, f, \sigma) d\Sigma}{\int_0^\infty G_{K,\Sigma}(\tau, f, \sigma) d\Sigma}, \quad (19)$$

or

$$\sigma_K(\tau, f, \sigma) = C(K) \sqrt{\frac{M_K^2(\tau, f, \sigma)}{P_K(\tau, f, \sigma)}}, \quad (20)$$



where

$$M_K^2(\tau, f, \sigma) = \int_0^\infty \Sigma^2 G_{K,\Sigma}(\tau, f, \sigma) d\Sigma \quad (21)$$

is the conditional second moment.

We will solve (15) - (16) and (17) by means of asymptotic techniques. In order to set up the expansion, it is convenient to introduce the following variables:

$$s = \frac{\tau}{T}, \quad x = f, \quad X = F, \quad y = \frac{\sigma}{v}, \quad Y = \frac{\Sigma}{v},$$

and the rescaled Green's function:

$$K_{X,Y}(s, x, y) = vTG_{X,vY}(Ts, x, vy).$$

In terms of these variables, the initial value problem (15)-(16) can be recast as:

$$\begin{aligned} \frac{\partial K}{\partial s} &= \frac{1}{2} \varepsilon y^2 \left( C(x)^2 \frac{\partial^2 K}{\partial x^2} + 2\rho C(x) \frac{\partial^2 K}{\partial x \partial y} + \frac{\partial^2 K}{\partial y^2} \right), \\ K(0, x, y) &= \delta(x - X, y - Y), \end{aligned} \quad (22)$$

where  $K = K_{X,Y}$ , and

$$\varepsilon = v^2 T. \quad (23)$$

It will be assumed that  $\varepsilon$  is small and it will serve as the parameter of our expansion. The heuristic picture behind this idea is that the volatility varies slower than the forward, and the rates of variability of  $f$  and  $\sigma/v$  are similar. The time  $T$  defines the time scale of the problem, and thus  $s$  is a natural dimensionless time variable. Expressed in terms of the new variables, our problem has a natural differential geometric content which is key to its solution.

Finally, let us write down the equations above for the normal SABR model:

$$\begin{aligned} \frac{\partial K}{\partial s} &= \frac{1}{2} \varepsilon y^2 \left( \frac{\partial^2 K}{\partial x^2} + \frac{\partial^2 K}{\partial y^2} \right), \\ K(0, x, y) &= \delta(x - X, y - Y). \end{aligned} \quad (24)$$

We will show later that this initial value problem has a closed form solution.

### 2.3 Boundary conditions at zero forward

The problem as we have formulated it so far is not complete. Since the value of the forward rate should be positive<sup>1</sup>, we have to specify a boundary condition for the Green's function at  $x = 0$ . Three commonly used boundary conditions are [9]:

- *Dirichlet (or absorbing) boundary condition.* We assume that the Green's function, denoted by  $K_{X,Y}^D(s, x, y)$ , vanishes at  $x = 0$ ,

$$K_{X,Y}^D(s, 0, y) = 0. \quad (25)$$

<sup>1</sup>Recent history shows that this is not always necessarily the case, but we regard such occurrences as anomalous.

- *Neumann (or reflecting) boundary condition.* We assume that the derivative of the Green's function at  $x = 0$ , normal to the boundary (and pointing outward), vanishes. Let  $K_{X,Y}^N(s, x, y)$  denote this Green's function; then

$$\frac{\partial}{\partial x} K_{X,Y}^N(s, 0, y) = 0. \quad (26)$$

- *Robin (or mixed) boundary condition.* The Green's function, which we shall denote by  $K_{X,Y}^R(s, x, y)$ , satisfies the following condition. Given  $\eta > 0$ ,

$$\left( -\frac{\partial}{\partial x} + \eta \right) K_{X,Y}^R(s, 0, y) = 0. \quad (27)$$

In this paper we will be concerned with the Dirichlet and Neumann boundary conditions only. Our task is tremendously simplified by the fact that the differential operator in (22) is invariant under the reflection  $x \rightarrow -x$  of the upper half plane. This allows one to construct the desired Green's functions by means of the method of images. Let  $K_{X,Y}(s, x, y)$  denote now the solution to (22) which ignores any boundary condition at  $x = 0^2$ . Then, one verifies readily that

$$K_{X,Y}^D(s, x, y) = K_{X,Y}(s, x, y) - K_{X,Y}(s, -x, y), \quad (28)$$

and

$$K_{X,Y}^N(s, x, y) = K_{X,Y}(s, x, y) + K_{X,Y}(s, -x, y) \quad (29)$$

are the solutions to the Dirichlet and Neumann problem, respectively.

Observe that the Green's functions corresponding to these different boundary conditions obey the following *conditioning inequalities*:

$$K^D \leq K \leq K^N. \quad (30)$$

Since the Dirichlet boundary condition corresponds to the stochastic process being killed at the boundary, the total mass of the Green's function is less than one:

$$\int K_{X,Y}^D(s, x, y) dx dy < 1. \quad (31)$$

The remaining probability is a Dirac's delta function at  $x = 0$ . On the other hand, for the free and Neumann boundary conditions,

$$\int K_{X,Y}(s, x, y) dx dy = \int K_{X,Y}^N(s, x, y) dx dy = 1, \quad (32)$$

and so they are *bona fide* probability distributions.

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<sup>2</sup>This is sometimes referred to as the Green's function with a *free boundary condition*.

## 2.4 Solving the initial value problem

It is easy to write down a formal solution to the initial value problem (22). Let  $L$  denote the partial differential operator

$$L = \frac{1}{2} y^2 \left( C(x)^2 \frac{\partial^2}{\partial x^2} + 2\rho C(x) \frac{\partial^2}{\partial x \partial y} + \frac{\partial^2}{\partial y^2} \right) \quad (33)$$

supplemented by a suitable boundary condition at  $x = 0$ . Consider the one-parameter semigroup of operators

$$U(s) = \exp(s\varepsilon L). \quad (34)$$

Then  $U$  solves the following initial value problem:

$$\begin{aligned} \frac{\partial U}{\partial s} &= \varepsilon L U, \\ U(0) &= I, \end{aligned}$$

and thus the Green's function  $K_{X,Y}(s, x, y)$  is the integral kernel of  $U(s)$ :

$$K_{X,Y}(s, x, y) = U(s)(x, y; X, Y). \quad (35)$$

In order to solve the problem (22) it is thus sufficient to construct the semigroup  $U(s)$  and find its integral kernel. Keeping in mind that our goal is to find an explicit formula for  $K_{X,Y}(s, x, y)$ , the strategy will be to represent  $L$  as the sum

$$L = L_0 + V, \quad (36)$$

where  $L_0$  is a second order differential operator with the property that

$$U_0(s) = \exp(s\varepsilon L_0) \quad (37)$$

can be represented in closed form. The operator  $V$  turns out to be a differential operator of first order, and we will treat it as a small perturbation of the operator  $L_0$ . The semigroup  $U(s)$  can now be expressed in terms of  $U_0(s)$  and  $V$  as

$$U(s) = Q(s) U_0(s). \quad (38)$$

Here, the operator  $Q(s)$  is given by the well known regular perturbation expansion:

$$Q(s) = I + \sum_{1 \leq n < \infty} \int_{0 \leq s_1 \leq \dots \leq s_n \leq s\varepsilon} e^{s_1 \text{ad}_{L_0}}(V) \dots e^{s_n \text{ad}_{L_0}}(V) ds_1 \dots ds_n, \quad (39)$$

where  $\text{ad}_{L_0}$  is the commutator with  $L_0$ :

$$\text{ad}_{L_0}(V) = L_0 V - V L_0. \quad (40)$$

We will use the first few terms in the expansion above in order to construct an accurate approximation to the Green's function  $K_{X,Y}(s, x, y)$ :

$$Q(s) = I + s\varepsilon V + \frac{1}{2} (s\varepsilon)^2 (\text{ad}_{L_0}(V) + V^2) + O((s\varepsilon)^3). \quad (41)$$

We shall disregard the convergence issues associated with this series, and use it solely as a tool to generate an asymptotic expansion.

### 3 Stochastic geometry of the state space

In solving our model we find that the normal SABR model represents Brownian motion on the Poincare plane. Generally, when  $\rho \neq 0$ , or  $C(x) \neq 1$ , the model amounts to Brownian motion on a two dimensional manifold, the *SABR plane*, perturbed by a drift term. In this section we summarize a number of basic facts about the differential geometry of the state space of the SABR model. The fundamental geometric structure is that of the Poincare plane. We will show that the state space of the SABR model can be viewed as a suitable deformation of the Poincare geometry.

#### 3.1 SABR plane

We begin by reviewing the Poincare geometry of the upper half plane which will serve as the standard state space of our model. For a full (and very readable) account of the theory the reader is referred to e.g. [1].

The *Poincare plane* (also known as the hyperbolic or Lobachevski plane) is the upper half plane  $\mathbb{H}^2 = \{(x, y) : y > 0\}$  equipped with the Poincare line element

$$ds^2 = \frac{dx^2 + dy^2}{y^2}. \quad (42)$$

This line element comes from the metric tensor given by

$$h = \frac{1}{y^2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}. \quad (43)$$

The Poincare plane admits a large group of symmetries. We introduce complex coordinates on  $\mathbb{H}^2$ ,  $z = x + iy$  (the defining condition then reads  $\text{Im}z > 0$ ), and consider a Moebius transformation

$$z' = \frac{az + b}{cz + d}, \quad (44)$$

where  $a, b, c, d$  are real numbers with  $ad - bc = 1$ . We verify easily the following two facts.

- Transformation (44) is a biholomorphic map of  $\mathbb{H}^2$  onto itself.
- The Poincare metric is invariant under (44).

As a consequence, the Lie group

$$SL(2, \mathbb{R}) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : a, b, c, d \in \mathbb{R}, ad - bc = 1 \right\} \quad (45)$$

acts holomorphically and isometrically on  $\mathbb{H}^2$ . This symmetry group plays very much the same role in the hyperbolic geometry as the Euclidean group in the usual Euclidean geometry of the plane  $\mathbb{R}^2$ .

In order to study the SABR model with the Dirichlet or Neumann boundary conditions at zero forward, we define the following reflection  $\theta : \mathbb{H}^2 \rightarrow \mathbb{H}^2$ :

$$\theta(x, y) = (-x, y) \quad (46)$$

(clearly, this is a reflection with respect to the  $y$ -axis). The key fact about  $\theta$  is that it is an involution, i.e.

$$\theta \circ \theta (z) = z. \quad (47)$$

One can also write  $\theta$  as  $\theta(z) = -\bar{z}$ , which shows that it is an anti-holomorphic map of  $\mathbb{H}^2$  into itself. It is easy to find the set of fixed points of  $\theta$ , namely the points on the Poincare plane which are left invariant by  $\theta$ :

$$\theta(x, y) = (x, y) \Leftrightarrow x = 0. \quad (48)$$

i.e. it is the positive  $y$ -axis.

Let  $d(z, Z)$  denotes the geodesic distance between two points  $z, Z \in \mathbb{H}^2$ ,  $z = x + iy$ ,  $Z = X + iY$ , i.e. the length of the shortest path connecting  $z$  and  $Z$ . There is an explicit expression for  $d(z, Z)$ :

$$\cosh d(z, Z) = 1 + \frac{|z - Z|^2}{2yY}, \quad (49)$$

where  $|z - Z|$  denotes the Euclidean distance between  $z$  and  $Z$ . In particular, if  $x = X$ , then  $d(z, Z) = |\log(y/Y)|$ . We also note that the reflection  $\theta$  is an isometry with respect to this metric,  $d(\theta(z), \theta(Z)) = d(z, Z)$ .

We also note that since  $\det(h) = y^{-4}$ , the invariant volume element on  $\mathbb{H}^2$  is given by

$$\begin{aligned} d\mu_h(z) &= \sqrt{\det(h)} \, dx \, dy \\ &= \frac{dx \, dy}{y^2}. \end{aligned} \quad (50)$$

The state space associated with the general SABR model has a somewhat more complicated geometry. Let  $\mathbb{S}^2$  denote the upper half plane  $\{(x, y) : y > 0\}$ , equipped with the following metric  $g$ :

$$g = \frac{1}{\sqrt{1 - \rho^2 y^2 C(x)^2}} \begin{pmatrix} 1 & -\rho C(x) \\ -\rho C(x) & C(x)^2 \end{pmatrix}. \quad (51)$$

This metric is a generalization of the Poincare metric: the case of  $\rho = 0$  and  $C(x) = 1$  reduces to the Poincare metric. In fact, the metric  $g$  is the pullback of the Poincare metric under a suitable diffeomorphism. To see this, we define a map  $\phi : \mathbb{S}^2 \rightarrow \mathbb{H}^2$  by

$$\phi(z) = \left( \frac{1}{\sqrt{1 - \rho^2}} \left( \int_0^x \frac{du}{C(u)} - \rho y \right), y \right), \quad (52)$$

where  $z = (x, y)$ . The Jacobian  $\nabla\phi$  of  $\phi$  is

$$\nabla\phi(z) = \begin{pmatrix} \frac{1}{\sqrt{1 - \rho^2} C(x)} & -\frac{\rho}{\sqrt{1 - \rho^2}} \\ 0 & 1 \end{pmatrix}, \quad (53)$$

and so  $\phi^*h = g$ , where  $\phi^*$  denotes the pullback of  $\phi$ . The manifold  $\mathbb{S}^2$  is thus isometrically diffeomorphic with the Poincare plane. A consequence of this fact is that we have an explicit formula for the geodesic distance  $\delta(z, Z)$  on  $\mathbb{S}^2$ :

$$\begin{aligned} \cosh \delta(z, Z) &= \cosh d(\phi(z), \phi(Z)) \\ &= 1 + \frac{\left(\int_X^x \frac{du}{C(u)}\right)^2 - 2\rho(y - Y) \int_X^x \frac{du}{C(u)} + (y - Y)^2}{2(1 - \rho^2)yY}, \end{aligned} \quad (54)$$

where  $z = (x, y)$  and  $Z = (X, Y)$  are two points on  $\mathbb{S}^2$ . Since  $\det(g) = y^{-4}C(x)^{-2}$ , the invariant volume element on  $\mathbb{S}^2$  is given by

$$\begin{aligned} d\mu_g(z) &= \sqrt{\det(g)} dx dy \\ &= \frac{dx dy}{C(x)y^2}. \end{aligned} \quad (55)$$

The manifold  $\mathbb{S}^2$  carries an isometric reflection  $\theta$  which commutes with (52):

$$\theta \circ \phi(z) = \phi \circ \theta(z), \quad (56)$$

i.e.  $\theta$  is inherited from the corresponding reflection  $\theta$  of the Poincare plane. To construct this reflection explicitly, we proceed as follows. The function  $\gamma : \mathbb{R} \rightarrow \mathbb{R}$  defined by

$$\gamma(x) = \int_0^x \frac{du}{C(u)} \quad (57)$$

is monotone increasing, and odd,

$$\gamma(-x) = -\gamma(x). \quad (58)$$

As a consequence, its inverse  $\gamma^{-1}$  exists. We set:

$$\theta(x, y) = (\gamma^{-1}(2\rho y - \gamma(x)), y), \quad (59)$$

and verify readily that it is an involution,  $\theta^2 = Id$ , and satisfies relation (56). It is easy to find the set of fixed points of  $\theta$ :

$$\theta(x, y) = (x, y) \Leftrightarrow x = \gamma^{-1}(\rho y). \quad (60)$$

Interestingly, in the case of zero correlation,  $\rho = 0$ ,  $\theta(x, y) = (-x, y)$ , i.e. it has the same form as in the Poincare case.

It will be convenient to use invariant notation. Let  $z^1 = x$ ,  $z^2 = y$ , and let  $\partial_\mu = \partial/\partial z^\mu$ ,  $\mu = 1, 2$ , denote the corresponding partial derivatives. We denote the components of  $g^{-1}$  by  $g^{\mu\nu}$ , and use  $g^{-1}$  and  $g$  to raise and lower the indices:  $z_\mu = g_{\mu\nu}z^\nu$ ,  $\partial^\mu = g^{\mu\nu}\partial_\nu = \partial/\partial z_\mu$ , where we sum over the repeated indices. Explicitly,

$$\begin{aligned} \partial^1 &= y^2 \left( C(x)^2 \partial_1 + \rho C(x) \partial_2 \right), \\ \partial^2 &= y^2 (\rho C(x) \partial_1 + \partial_2). \end{aligned}$$

Consequently, the initial value problem (22) can be written in the following geometric form:

$$\begin{aligned}\frac{\partial}{\partial s} K_Z(s, z) &= \frac{1}{2} \varepsilon \partial^\mu \partial_\mu K_Z(s, z), \\ K_Z(0, z) &= \delta(z - Z).\end{aligned}\tag{61}$$

### 3.2 Brownian motion on the SABR plane

It is no coincidence that the SABR model leads to the Poincare geometry. Recall [14] that the Brownian motion on the Poincare plane is described by the following system of stochastic differential equations:

$$\begin{aligned}dX_t &= Y_t dW_t, \\ dY_t &= Y_t dZ_t,\end{aligned}\tag{62}$$

with the two Wiener processes  $W_t$  and  $Z_t$  satisfying

$$\mathbf{E}[dW_t dZ_t] = 0.\tag{63}$$

Comparing this with the special case of the normal SABR model (8), we see that (8) reduces to (62) once we have made the following identifications:

$$\begin{aligned}X_t &= F_{v^2 t}, \\ Y_t &= \frac{1}{v} \Sigma_{v^2 t},\end{aligned}\tag{64}$$

and used the scaling properties of a Wiener process:

$$\begin{aligned}dW_{v^2 t} &= v dW_t, \\ dZ_{v^2 t} &= v dZ_t.\end{aligned}$$

Note that the system (62) can easily be solved in closed form: its solution is given by

$$\begin{aligned}X_t &= X_0 + Y_0 \int_0^t \exp\left(Z(s) - \frac{s^2}{2}\right) dW(s), \\ Y_t &= Y_0 \exp\left(Z_t - \frac{t^2}{2}\right).\end{aligned}\tag{65}$$

Let us now compare the SABR dynamics with that of the diffusion on the SABR plane. In order to find the dynamics of Brownian motion on the SABR plane we use the fact that there is a mapping (namely, (52)) of  $\mathbb{S}^2$  into  $\mathbb{H}^2$ . Using this mapping and Ito's lemma yields the following system

$$\begin{aligned}dX_t &= \frac{1}{2} Y_t^2 C(X_t) C'(X_t) dt + Y_t C(X_t) dW_t, \\ dY_t &= Y_t dZ_t,\end{aligned}\tag{66}$$

with the two Wiener processes  $W_t$  and  $Z_t$  satisfying

$$\mathbf{E}[dW_t dZ_t] = \rho dt. \quad (67)$$

Note that this is not exactly the SABR model dynamics. Indeed, one can regard the SABR model as the perturbation of the Brownian motion on the SABR plane by the drift term  $-\frac{1}{2} Y_t^2 C(X_t) C'(X_t) dt$ .

As in the case of the Poincare plane, it is possible to represent the solution to the system (66) explicitly:

$$\begin{aligned} \int_{X_0}^{X_t} \frac{du}{C(u)} &= Y_0 \int_0^t \exp\left(Z(s) - \frac{s^2}{2}\right) dW(s), \\ Y_t &= Y_0 \exp\left(Z_t - \frac{t^2}{2}\right). \end{aligned} \quad (68)$$

Parenthetically, we note that, within Stratonovich's calculus, (66) can be written as

$$\begin{aligned} dX_t &= Y_t C(X_t) \circ dW_t, \\ dY_t &= Y_t \circ dZ_t. \end{aligned}$$

Therefore, the stochastic differential equations of the SABR model, if interpreted according to Stratonovich, describe the dynamics of Brownian motion on the SABR plane.

### 3.3 Laplace-Beltrami operator on the SABR plane

Recall that the Laplace-Beltrami operator  $\Delta_g$  on a Riemannian manifold  $\mathcal{M}$  with metric tensor  $g$  is defined by

$$\Delta_g f = \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^\mu} \left( \sqrt{\det g} g^{\mu\nu} \frac{\partial f}{\partial x^\nu} \right), \quad (69)$$

where  $f$  is a smooth function on  $\mathcal{M}$ . It is a natural generalization of the familiar Laplace operator to spaces with non-Euclidean geometry. Its importance for probability theory comes from the fact that it serves as the infinitesimal generator of Brownian motion on such spaces (see e.g. [7], [8], [14]).

In the case of the Poincare plane, the Laplace-Beltrami operator has the form:

$$\Delta_h = y^2 \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right). \quad (70)$$

As anticipated by our discussion in Section 3.2, this operator is closely related to the operator  $L$  in the normal SABR model. In fact, in this case,

$$L = \frac{1}{2} \Delta_h, \quad (71)$$



and thus the problem (24) turns out to be the initial value problem the heat equation on  $\mathbb{H}^2$ :

$$\begin{aligned}\frac{\partial K_Z}{\partial s} &= \frac{1}{2} \varepsilon \Delta_h K_Z, \\ K_Z(0, z) &= \delta(z - Z)\end{aligned}\tag{72}$$

The key fact is that the Green's function for this equation can be represented in closed form,

$$K_Z^h(s, z) = \frac{e^{-s\varepsilon/8}\sqrt{2}}{(2\pi s\varepsilon)^{3/2} Y^2} \int_{d(z, Z)}^{\infty} \frac{ue^{-u^2/2s\varepsilon}}{\sqrt{\cosh u - \cosh d(z, Z)}} du.\tag{73}$$

This formula was originally derived by McKean [16] (see also [14] and references therein). We have added the superscript  $h$  to indicate that this Green's function is associated with the Poincare metric. In Appendix A we outline an elementary derivation of this fact.

Let us now extend the discussion above to the general case. We note first that, except for the case of  $C(x) = 1$ , the operator  $\partial^\mu \partial_\mu$  does not coincide with the Laplace-Beltrami operator  $\Delta_g$  on  $\mathbb{S}^2$  associated with the metric (51). It is, however, easy to verify that

$$\begin{aligned}\partial^\mu \partial_\mu f &= \Delta_g f - \frac{1}{\sqrt{\det g}} \frac{\partial}{\partial x^\nu} \left( \sqrt{\det g} g^{\mu\nu} \right) \frac{\partial f}{\partial x^\mu} \\ &= \Delta_g f - \frac{1}{\sqrt{1-\rho^2}} y^2 C C' \frac{\partial f}{\partial x},\end{aligned}$$

and thus

$$\begin{aligned}L &= \frac{1}{2} \Delta_g - \frac{1}{2\sqrt{1-\rho^2}} y^2 C C' \frac{\partial}{\partial x} \\ &= L_0 + V,\end{aligned}$$

where  $L_0$  is essentially the Laplace-Beltrami operator:

$$L_0 = \frac{1}{2} \Delta_g,\tag{74}$$

and  $V(x)$  is lower order:

$$V = -\frac{1}{2\sqrt{1-\rho^2}} y^2 C(x) C'(x) \frac{\partial}{\partial x}.\tag{75}$$

Let us first focus on the Laplace-Beltrami operator  $\Delta_g$ . The key property of the Laplace-Beltrami operator is its invariance under a diffeomorphism. In particular, this implies that

$$\Delta_g = \phi^{-1} \circ \Delta_h \circ \phi,\tag{76}$$

and, hence, the heat equation

$$\frac{\partial K}{\partial s} = \frac{1}{2} \varepsilon \Delta_g K.$$

on  $\mathbb{S}^2$  can be solved in closed form! The Green's function  $K_Z^g(s, z)$  of this equation is related to (73) by

$$K_Z^g(s, z) = \det(\nabla\phi(Z)) K_{\phi(Z)}^h(s, \phi(z)). \quad (77)$$

Explicitly,

$$K_Z^g(s, z) = \frac{e^{-s\varepsilon/8}\sqrt{2}}{(2\pi s\varepsilon)^{3/2}\sqrt{1-\rho^2}Y^2C(X)} \int_{\delta}^{\infty} \frac{ue^{-u^2/2s\varepsilon}}{\sqrt{\cosh u - \cosh \delta}} du, \quad (78)$$

where  $\delta = \delta(z, Z)$  is the geodesic distance (54) on  $\mathbb{S}^2$ . This is the explicit representation of the integral kernel of the operator  $U_0(s)$ .

## 4 Asymptotic expansion

In principle, we have now completed our task of solving the initial value problem (24). Indeed, its solution is given by

$$K_Z(s, z) = Q(s) K_Z^g(s, z), \quad (79)$$

where  $Q(s)$  is the perturbation expansion given by (39). In order to produce clear results that can readily be used in practice we perform now a perturbation expansion on the expression above. Our method allows one to calculate the Green's function of the model to the desired order of accuracy.

Let us start with the Green's function  $K_Z^h(s, z)$  which is defined on the Poincare plane. In Appendix B we derived an asymptotic expansion (121) for the heat kernel on the Poincare plane. After rescaling as in (110), we arrive at

$$K_Z^h(s, z) = \frac{1}{2\pi\lambda Y^2} \exp\left(-\frac{d^2}{2\lambda}\right) \times \sqrt{\frac{d}{\sinh d}} \left(1 - \frac{1}{8} \left(\frac{d \coth d - 1}{d^2} + 1\right) \lambda + O(\lambda^2)\right),$$

where we have introduced a new variable,

$$\lambda = s\varepsilon. \quad (80)$$

We can now extend the expression to the general Green's function  $K_Z^g(s, z)$ . Using (77) or (78) we find that  $K_Z^g(s, z)$  has the following asymptotic expansion:

$$K_Z^g(s, z) = \frac{1}{2\pi\lambda\sqrt{1-\rho^2}Y^2C(X)} \exp\left(-\frac{\delta^2}{2\lambda}\right) \times \sqrt{\frac{\delta}{\sinh \delta}} \left(1 - \frac{1}{8} \left(\frac{\delta \coth \delta - 1}{\delta^2} + 1\right) \lambda + O(\lambda^2)\right).$$

To complete the calculation in the case of general  $C(x)$  we need to take into account the contribution to the Green's function coming from perturbation  $V$  defined in (75). Let us define the function:

$$\begin{aligned} q(z, Z) &= \sinh \delta(z, Z) V \delta(z, Z) \\ &= -\frac{yC'(x)}{2(1-\rho^2)^{3/2}Y} \left( \int_X^x \frac{du}{C(u)} - \rho(y-Y) \right). \end{aligned} \quad (81)$$

From (121) and (122),

$$\begin{aligned} K_Z(s, z) &= (I + \lambda V) K_Z^g(s, z) \\ &= \frac{1}{\sqrt{1-\rho^2} Y^2 C(X)} \left( K_Z(s, z) + \lambda \frac{q}{\sinh \delta} \frac{\partial}{\partial \delta} K_Z(s, z) \right), \end{aligned} \quad (82)$$

which yields the following asymptotic formula for the Green's function:

$$\begin{aligned} K_Z(s, z) &= \frac{1}{2\pi\lambda\sqrt{1-\rho^2} Y^2 C(X)} \exp\left(-\frac{\delta^2}{2\lambda}\right) \\ &\times \sqrt{\frac{\delta}{\sinh \delta}} \left[ 1 - \frac{\delta}{\sinh \delta} q \right. \\ &\left. - \left( \frac{1}{8} + \frac{\delta \coth \delta - 1}{8\delta^2} - \frac{3(1 - \delta \coth \delta) + \delta^2}{8\delta \sinh \delta} q \right) \lambda + O(\lambda^2) \right]. \end{aligned} \quad (83)$$

In a way, this is the central result of this paper. It gives us a precise asymptotic behavior of the Green's function of the SABR model, as  $\lambda \rightarrow 0$ .

## 5 Volatility smile

We are now ready to complete our analysis. Given the explicit form of the approximate Green's function, we can calculate (via another asymptotic expansion) the marginal probability distribution. Comparing the result with the normal probability distribution allows us to find the implied normal and lognormal volatilities, as functions of the model parameters. We conclude this section by deriving explicit formulas for the case of the CEV model  $C(x) = x^\beta$  and the shifted lognormal model  $C(x) = x + a$ .

### 5.1 Marginal transition probability

First, we integrate the asymptotic joint density over the terminal volatility variable  $Y$  to find the marginal density for the forward  $x$ . To within  $O(\lambda^2)$ ,

$$\begin{aligned} P_X(s, x, y) &= \int_0^\infty K_Z(s, z) dY \\ &= \frac{1}{2\pi\lambda\sqrt{1-\rho^2} C(X)} \int_0^\infty e^{-\delta^2/2\lambda} \sqrt{\frac{\delta}{\sinh \delta}} \left[ 1 - \frac{\delta}{\sinh \delta} q \right. \\ &\left. - \frac{1}{8} \lambda \left( 1 + \frac{\delta \coth \delta - 1}{\delta^2} - \frac{3(1 - \delta \coth \delta) + \delta^2}{\delta \sinh \delta} q \right) \right] \frac{dY}{Y^2}. \end{aligned} \quad (84)$$

Here the metric  $\delta(z, Z)$  is defined implicitly by (54). We evaluate this integral asymptotically by using Laplace's method (steepest descent). This analysis is carried out in Appendix B.2. The key step is to analyze the argument  $Y$  of the exponent

$$\phi(Y) = \frac{1}{2} \delta(z, Z)^2, \quad (85)$$

in order to find the point  $Y_0$  where this function is at a minimum. Let us introduce the notation:

$$\zeta = \frac{1}{y} \int_X^x \frac{du}{C(u)}.$$

Since  $yC(u)$  is basically the rescaled volatility at forward  $u$ ,  $1/\zeta$  represents the average volatility between today's forward  $x$  and at option's strike  $X$ . In other words,  $\zeta$  represents how "easy" it is to reach the strike  $X$ . Some algebra shows that the minimum of (85) occurs at  $Y_0 = Y_0(\zeta, y)$ , where

$$Y_0 = y\sqrt{\zeta^2 - 2\rho\zeta + 1}. \quad (86)$$

The meaning of  $Y_0$  is clear: it is the "most likely value" of  $Y$ , and thus  $Y_0C(X)$  (when expressed in the original units) should be the leading contribution to the observed implied volatility. Also, let  $D(\zeta)$  denote the value of  $\delta(z, Z)$  with  $Y = Y_0$ . Explicitly,

$$D(\zeta) = \log \frac{\sqrt{\zeta^2 - 2\rho\zeta + 1} + \zeta - \rho}{1 - \rho}. \quad (87)$$

The analysis in Appendix B.3 shows that the probability distribution for  $x$  is Gaussian in this minimum distance, at least to leading order. Specifically, it is shown there that to within  $O(\lambda^2)$ ,

$$\begin{aligned} P_X(s, x, y) = & \frac{1}{\sqrt{2\pi\lambda}} \frac{1}{yC(X)I^{3/2}} \exp\left\{-\frac{D^2}{2\lambda}\right\} \left\{1 + \frac{yC'(x)D}{2\sqrt{1-\rho^2}I}\right. \\ & - \frac{1}{8}\lambda \left[1 + \frac{yC'(x)D}{2\sqrt{1-\rho^2}I} + \frac{6\rho yC'(x)}{\sqrt{1-\rho^2}I^2} \cosh(D)\right. \\ & \left. \left. - \left(\frac{3(1-\rho^2)}{I} + \frac{3yC'(x)(5-\rho^2)D}{2\sqrt{1-\rho^2}I^2}\right) \frac{\sinh(D)}{D}\right] + \dots\right\}, \end{aligned} \quad (88)$$

where

$$\begin{aligned} I(\zeta) &= \sqrt{\zeta^2 - 2\rho\zeta + 1} \\ &= \cosh D(\zeta) - \rho \sinh D(\zeta). \end{aligned} \quad (89)$$

As this expression may be useful on its own, we rewrite it in terms of the original variables:

$$\begin{aligned}
P_F(\tau, f, \sigma) &= \frac{1}{\sqrt{2\pi\tau}} \frac{1}{\sigma C(F) I^{3/2}} \exp\left\{-\frac{D^2}{2\tau v^2}\right\} \left\{1 + \frac{\sigma C'(f) D}{2v\sqrt{1-\rho^2} I} \right. \\
&\quad - \frac{1}{8} \tau v^2 \left[1 + \frac{\sigma C'(f) D}{2v\sqrt{1-\rho^2} I} + \frac{6\rho\sigma C'(f)}{v\sqrt{1-\rho^2} I^2} \cosh(D) \right. \\
&\quad \left. \left. - \left(\frac{3(1-\rho^2)}{I} + \frac{3\sigma C'(f)(5-\rho^2) D}{2v\sqrt{1-\rho^2} I^2}\right) \frac{\sinh(D)}{D}\right] + \dots \right\}, \tag{90}
\end{aligned}$$

where we have slightly abused the notation. This is the desired asymptotic form of the marginal probability distribution.

## 5.2 Implied volatility

The normal implied volatility is given by (2.2), and we are thus left with the task of calculating the conditional second moment. Explicitly,

$$\begin{aligned}
M_X^2(s, x, y) &= \int_0^\infty Y^2 K_Z(s, z) dY \\
&= \frac{1}{2\pi\lambda\sqrt{1-\rho^2} C(X)} \int_0^\infty e^{-\delta^2/2\lambda} \sqrt{\frac{\delta}{\sinh \delta}} \left[1 - \frac{\delta}{\sinh \delta} q \right. \\
&\quad \left. - \frac{1}{8} \lambda \left(1 + \frac{\delta \coth \delta - 1}{\delta^2} - \frac{3(1-\delta \coth \delta) + \delta^2}{\delta \sinh \delta} q\right)\right] dY. \tag{91}
\end{aligned}$$

In Appendix B.3 we show that

$$\begin{aligned}
M_X^2(s, x, y) &= \frac{1}{\sqrt{2\pi\lambda}} \frac{\sqrt{I}}{yC(X)} \exp\left\{-\frac{D^2}{2\lambda}\right\} \left\{1 + \frac{yC'(x) D}{2\sqrt{1-\rho^2} I} \right. \\
&\quad + \frac{1}{8} \lambda \left[1 - \frac{yC'(x) D}{2\sqrt{1-\rho^2} I} + \frac{2\rho yC'(x)}{\sqrt{1-\rho^2} I^2} \cosh(D) \right. \\
&\quad \left. \left. + \left(\frac{3(1-\rho^2)}{I} + \frac{2yC'(x)(3\rho^2-4) D}{\sqrt{1-\rho^2} I^2}\right) \frac{\sinh(D)}{D}\right] + \dots \right\}.
\end{aligned}$$

Despite their complicated appearances, the two expressions have a lot in common, and their ratio has a rather simple form. After the dust settles, we find that

$$\begin{aligned}
\sigma_K(\tau, f, \sigma)^2 &= \sigma^2 C(K)^2 I(\zeta) \\
&\quad \times \left[1 + \frac{2\sigma C'(f)(\rho \cosh(D) - \sinh(D))}{\sigma C'(f) D I + 2\sqrt{1-\rho^2} I^2 v} \tau v^2 + \dots\right], \tag{92}
\end{aligned}$$

or

$$\begin{aligned} \sigma_K(\tau, f, \sigma) &= \sigma C(K) I(\zeta) \\ &\times \left[ 1 + \frac{\sigma C'(f) (\rho \cosh(D) - \sinh(D))}{\sigma C'(f) DI + 2\sqrt{1-\rho^2} I^2 v} \tau v^2 + \dots \right]. \end{aligned} \quad (93)$$

This is a refinement of the original asymptotic expression for implied volatility in the SABR model.

It is easy to apply this formula to the specific choice of the function  $C(f)$ . In case of the stochastic CEV model,  $C(f) = f^\beta$ , with  $0 < \beta \leq 1$ . If  $\beta = 1$ , then

$$\zeta = \frac{v}{\sigma} \log\left(\frac{f}{F}\right). \quad (94)$$

For  $0 < \beta < 1$ ,

$$\zeta = \frac{v}{\sigma} \frac{f^{1-\beta} - F^{1-\beta}}{1-\beta}. \quad (95)$$

In the shifted lognormal model,  $C(f) = f + a$ , where  $a > 0$ . Consequently,

$$\zeta = \frac{v}{\sigma} \log\left(\frac{f+a}{F+a}\right). \quad (96)$$

### 5.3 Implied volatility at low strikes

Our analysis so far has been based on the assumption that we were working with the free boundary condition. We are now ready to tackle the Dirichlet and Neumann boundary conditions, and thus address the issue of low strikes in the SABR model.

As explained in Section 2.3, the Green's functions corresponding to the Dirichlet and Neumann boundary conditions at zero forward can easily be calculated, using the method of images, in terms of the Green's function with free boundary conditions. This, in turn, allows us to express the marginal probability distributions in terms of (90):

$$\begin{aligned} P_F^{\text{Dirichlet}}(\tau, f, \sigma) &= P_F(\tau, f, \sigma) - P_F(\tau, -f, \sigma), \\ P_F^{\text{Neumann}}(\tau, f, \sigma) &= P_F(\tau, f, \sigma) + P_F(\tau, -f, \sigma). \end{aligned} \quad (97)$$

Analogous formulas hold for the conditional second moments. We can now easily find asymptotic expressions for the implied volatilities corresponding to these boundary conditions.

In order to keep the appearance of the otherwise unwieldy formulas reasonable, we shall introduce some additional notation. Let

$$I^\theta = I(\zeta^\theta), \quad (98)$$

where

$$\zeta^\theta = \frac{1}{y} \int_X^{\theta(x)} \frac{du}{C(u)}. \quad (99)$$

Furthermore, let us define the ratio

$$\gamma = \sqrt{\frac{I}{I\theta}}. \quad (100)$$

and note that  $\gamma < 1$ . Finally, we set:

$$\eta = \begin{cases} -1, & \text{for the Dirichlet boundary condition,} \\ 0, & \text{for the free boundary condition.} \\ 1, & \text{for the Neumann boundary condition.} \end{cases} \quad (101)$$

It is now easy to see that:

$$\begin{aligned} \sigma_K^\eta(\tau, f, \sigma) &= \sigma C(K) I \frac{1}{\sqrt{1 - \eta\gamma + \eta^2\gamma^2}} \\ &\times \left[ 1 + \frac{\sigma C'(f)(\rho \cosh(D) - \sinh(D))}{\sigma C'(f) DI + 2\sqrt{1 - \rho^2} I^2 v} \tau v^2 + \dots \right]. \end{aligned} \quad (102)$$

It is worthwhile to note that for large strikes all three of these quantities are practically equal, and one might as well work with the free boundary condition expression. Indeed, in this case,  $\gamma \approx 0$ , and so  $\sqrt{1 - \eta\gamma + \eta^2\gamma^2} \approx 1$ . Also, we see from this expression that, at least asymptotically,

$$\sigma_K^{\text{Dirichlet}}(\tau, f, \sigma) < \sigma_K^{\text{free}}(\tau, f, \sigma) < \sigma_K^{\text{Neumann}}(\tau, f, \sigma). \quad (103)$$

This result is intuitively clear, and (102) quantifies it in a way that can be used for position management purposes. The decision which boundary condition to adopt should be made based on specific market conditions.

## A Heat equation on the Poincare plane

In this appendix we present an elementary derivation of the explicit representation of the Green's function for the heat equation on  $\mathbb{H}^2$ . This explicit formula has been known for a long time (see e.g. [16]), and we include its construction here in order to make our calculations self-contained.

### A.1 Lower bound on the Laplace-Beltrami operator

We shall first establish a lower bound on the spectrum of the Laplace-Beltrami operator on the Poincare plane. Let  $\mathcal{H} = L^2(\mathbb{H}^2, d\mu_h)$  denote the Hilbert space of complex functions on  $\mathbb{H}^2$  which are square integrable with respect to the measure (50). The inner product on this space is thus given by:

$$(\Phi|\Psi) = \int_{\mathbb{H}^2} \overline{\Phi(z)} \Psi(z) \frac{dx dy}{y^2}. \quad (104)$$

It is easy to verify that the Laplace-Beltrami operator  $\Delta_h$  is self-adjoint with respect to this inner product.

Consider now the first order differential operator  $Q$  on  $\mathcal{H}$  defined by

$$Q = i \left( y \frac{\partial}{\partial y} - \frac{1}{2} \right) + y \frac{\partial}{\partial x}. \quad (105)$$

Its hermitian adjoint with respect to (104) is

$$Q^\dagger = i \left( y \frac{\partial}{\partial y} - \frac{1}{2} \right) - y \frac{\partial}{\partial x}, \quad (106)$$

and we verify readily that

$$\frac{1}{2} (QQ^\dagger + Q^\dagger Q) = -\Delta_h - \frac{1}{4}. \quad (107)$$

This implies that

$$\begin{aligned} (\Phi | -\Delta_h \Phi) &= \frac{1}{2} (\Phi | QQ^\dagger \Phi) + \frac{1}{2} (\Phi | Q^\dagger Q \Phi) + \frac{1}{4} (\Phi | \Phi) \\ &= \frac{1}{2} (Q^\dagger \Phi | Q^\dagger \Phi) + \frac{1}{2} (Q \Phi | Q \Phi) + \frac{1}{4} (\Phi | \Phi) \\ &\geq \frac{1}{4} (\Phi | \Phi), \end{aligned}$$

where we have used the fact that  $(\Psi | \Psi) \geq 0$ , for all functions  $\Psi \in \mathcal{H}$ . As a consequence, we have established that the spectrum of the operator  $-\Delta_h$  is bounded from below by  $\frac{1}{4}$ ! This fact was first proved in [16].

## A.2 Construction of the Green's function

Let us now consider the the following initial value problem:

$$\begin{aligned} \frac{\partial}{\partial s} G_Z(s, z) &= \Delta_h G_Z(s, z), \\ G_Z(0, z) &= Y^2 \delta(z - Z), \end{aligned} \quad (108)$$

where  $z, Z \in \mathbb{H}^2$ . In addition, we require that

$$G_Z(s, z) \rightarrow 0, \quad \text{as } d(z, Z) \rightarrow \infty. \quad (109)$$

Note that, up to the factor of  $Y^2$  in front of the delta function and a trivial time rescaling, this is exactly the initial value problem (72):

$$G_Z(s, z) = Y^2 K_Z(2s/\varepsilon, z). \quad (110)$$

The Green's function  $G_Z(s, z)$  is also referred to as the heat kernel<sup>3</sup> on  $\mathbb{H}^2$ . The reason for inserting the factor of  $Y^2$  in front of  $\delta(z - Z)$  is that the distribution  $Y^2 \delta(z - Z)$

<sup>3</sup>It is the integral kernel of the semigroup of operators generated by the heat equation.



is invariant under the action (44) of the Lie group  $SL(2, \mathbb{R})$ . In fact, we verify readily that

$$Y^2 \delta(z - Z) = \frac{1}{\pi} \delta(\cosh d(z, Z) - 1).$$

Now, since the initial value problem (109) is invariant under  $SL(2, \mathbb{R})$ , its solution must be invariant and thus a function of  $d(z, Z)$  only. Let  $r = \cosh d(z, Z)$ , and write  $G_Z(s, z) = \varphi(s, r)$ . Then the heat equation in (109) takes the form

$$\frac{\partial}{\partial s} \varphi(s, r) = (r^2 - 1) \frac{\partial^2}{\partial r^2} \varphi(s, r) + 2r \frac{\partial}{\partial r} \varphi(s, r). \quad (111)$$

We have established above that the operator  $-\Delta_h$  is self-adjoint on the Hilbert space  $\mathcal{H}$ , and its spectrum is bounded from below by  $\frac{1}{4}$ . Therefore, we shall seek the solution as the Laplace transform

$$\varphi(s, r) = \int_{1/4}^{\infty} e^{-s\lambda} L(\lambda, r) d\lambda \quad (112)$$

which yields the following ordinary differential equation:

$$(1 - r^2) \frac{d^2}{dr^2} L(\lambda, r) - 2r \frac{d}{dr} L(\lambda, r) + \lambda L(\lambda, r) = 0. \quad (113)$$

We write

$$\lambda = \nu(\nu + 1),$$

where

$$\begin{aligned} \nu &= -\frac{1}{2} \pm i\sqrt{\lambda - \frac{1}{4}} \\ &= -\frac{1}{2} \pm i\omega, \end{aligned}$$

and recognize in (113) the Legendre equation. Note that, as a consequence of the inequality  $\lambda \geq \frac{1}{4}$ ,  $\omega$  is real and  $\operatorname{Re} \nu = -\frac{1}{2}$ .

In the remainder of this appendix, we will use the well known properties of the solutions to the Legendre equation, and follow Chapters 7 and 8 of Lebedev's book on special functions [15]. The general solution to (113) is a linear combination of the Legendre functions of the first and second kinds,  $P_{-1/2+i\omega}(r)$  and  $Q_{-1/2+i\omega}(r)$ , respectively:

$$L\left(\frac{1}{4} + \omega^2, r\right) = A_\omega P_{-1/2+i\omega}(r) + B_\omega Q_{-1/2+i\omega}(r). \quad (114)$$

As  $d \rightarrow 0$  (which is equivalent to  $r \rightarrow 1$ ),

$$Q_{-1/2+i\omega}(\cosh d) \sim \text{const} \log d, \quad (115)$$

which would imply that  $\varphi(s, \cosh d)$  is singular at  $d = 0$ , for all values of  $s > 0$ . Since this is impossible, we conclude that  $B_\omega = 0$ . Note that, on the other hand,

$$P_{-1/2+i\omega}(1) = 1, \quad (116)$$

i.e.  $P_{-1/2+i\omega}(\cosh d)$  is non-singular at  $d = 0$ .

We will now invoke the Mehler-Fock transformation of a function<sup>4</sup>:

$$\tilde{f}(\omega) = \int_1^\infty f(r) P_{-1/2+i\omega}(r) dr, \quad (117)$$

$$f(r) = \int_0^\infty \tilde{f}(\omega) P_{-1/2+i\omega}(r) \omega \tanh(\pi\omega) d\omega. \quad (118)$$

In particular, (116) implies that the Mehler-Fock transform of  $\delta(r-1)$  is 1, and thus (remember that we need to divide  $\delta(r-1)$  by  $\pi$ ):

$$A_\omega = \frac{1}{2\pi} \tanh(\pi\omega).$$

Now, the Legendre function of the first kind  $P_{-1/2+i\omega}(r)$  has the following integral representation:

$$P_{-1/2+i\omega}(\cosh d) = \frac{\sqrt{2}}{\pi} \coth(\pi\omega) \int_d^\infty \frac{\sin(\omega u)}{\sqrt{\cosh u - \cosh d}} du, \quad (119)$$

which is valid for all real  $\omega$ . Therefore

$$L\left(\frac{1}{4} + \omega^2, \cosh d\right) = \frac{1}{\sqrt{2}\pi^2} \int_d^\infty \frac{\sin(\omega u)}{\sqrt{\cosh u - \cosh d}} du,$$

and we can easily carry out the integration in (112) to obtain

$$G_Z(s, z) = \frac{e^{-s/4}\sqrt{2}}{(4\pi s)^{3/2}} \int_{d(z, Z)}^\infty \frac{ue^{-u^2/4s}}{\sqrt{\cosh u - \cosh d(z, Z)}} du. \quad (120)$$

This is McKean's closed form representation of the Green's function of the heat equation on the Poincare plane [16].

Going back to the original normalization conventions of (72) yields formula (73).

## B Some asymptotic expansions

In this appendix we collect a number of asymptotic expansions used in this paper.

### B.1 Asymptotics of the McKean kernel

We shall first establish a short time asymptotic expansion of McKean's kernel. This expansion plays a key role in the analysis of the Green's function of the SABR model.

In the right hand side of (120) we substitute  $u = \sqrt{4sw + d^2}$ :

$$G_Z(s, z) = \frac{e^{-s/4}\sqrt{2}}{4\pi^{3/2}\sqrt{s}} e^{-d^2/4s} \int_0^\infty \frac{e^{-w} dw}{\sqrt{\cosh \sqrt{4sw + d^2} - \cosh d}}.$$

<sup>4</sup>Strictly speaking, we will deal with distributions rather than functions. A rigor oriented reader can easily recast the following calculations into respectable mathematics.

Expanding the integrand in powers of  $s$  yields

$$\frac{1}{\sqrt{\cosh \sqrt{4sw} + d^2 - \cosh d}} = \sqrt{\frac{d}{\sinh d}} \times \left( \frac{1}{\sqrt{2sw}} - \frac{d \coth d - 1}{4d^2} \sqrt{2sw} + O(s^{3/2}) \right).$$

Integrating term by term over  $w$  we find that

$$G_Z(s, z) = \frac{e^{-s/4}}{4\pi s} \exp\left(-\frac{d^2}{4s}\right) \times \sqrt{\frac{d}{\sinh d}} \left( 1 - \frac{1}{4} \frac{d \coth d - 1}{d^2} s + O(s^2) \right),$$

and we thus obtain the following asymptotic expansion of the McKean kernel:

$$G_Z(s, z) = \frac{1}{4\pi s} \exp\left(-\frac{d^2}{4s}\right) \times \sqrt{\frac{d}{\sinh d}} \left[ 1 - \frac{1}{4} \left( \frac{d \coth d - 1}{d^2} + 1 \right) s + O(s^2) \right], \quad (121)$$

Taking the derivative of  $G_Z(s, z)$  with respect of  $d(z, Z)$  in the expansion above, we find that

$$\frac{\partial}{\partial d} G_Z(s, z) = \frac{1}{4\pi s} \exp\left(-\frac{d^2}{4s}\right) \times \sqrt{\frac{d}{\sinh d}} \left[ -\frac{d}{2s} + \frac{d}{8} \left( 1 + 3 \frac{1 - d \coth d}{d^2} \right) + O(s) \right]. \quad (122)$$

## B.2 Laplace's method

Next we review the Laplace method (see e.g. [3], [2]) which allows one to evaluate approximately integrals of the form:

$$\int_0^\infty f(u) e^{-\phi(u)/\epsilon} du. \quad (123)$$

We use this method in order to evaluate the marginal probability distribution for the Green's function.

In the integral (123),  $\epsilon$  is a small parameter, and  $f(u)$  and  $\phi(u)$  are smooth functions on the interval  $[0, \infty)$ <sup>5</sup>. We also assume that  $\phi(u)$  has a unique minimum  $u_0$  inside the interval with  $\phi''(u_0) > 0$ . The idea is that, as  $\epsilon \rightarrow 0$ , the value of the integral is dominated by the quadratic approximation to  $\phi(u)$  around  $u_0$ .

<sup>5</sup>It can be an arbitrary interval.

More precisely, we have the following asymptotic expansion. As  $\epsilon \rightarrow 0$ ,

$$\int_0^\infty f(u) e^{-\phi(u)/\epsilon} du = \sqrt{\frac{2\pi\epsilon}{\phi''(u_0)}} e^{-\phi(u_0)/\epsilon} \times \left\{ f(u_0) + \epsilon \left[ \frac{f''(u_0)}{2\phi''(u_0)} - \frac{\phi^{(4)}(u_0) f(u_0)}{8\phi''(u_0)^2} - \frac{f'(u_0) \phi^{(3)}(u_0)}{2\phi''(u_0)^2} + \frac{5\phi^{(3)}(u_0)^2 f(u_0)}{24\phi''(u_0)^3} \right] + O(\epsilon^2) \right\}. \quad (124)$$

To generate this expansion, we first expand  $f(u)$  and  $\phi(u)$  in Taylor series around  $u_0$  to orders 2 and 4, respectively (keep in mind that the first order term in the expansion of  $\phi(u)$  is zero). Then, expanding the regular terms in the exponential, we organize the integrand as  $e^{-\phi''(u_0)(u-u_0)^2/2\epsilon}$  times a polynomial in  $\epsilon$ . In the limit  $\epsilon \rightarrow 0$ , the integral reduces to calculating moments of the Gaussian measure; the result is (124). It is straightforward to compute terms of order higher than 1 in  $\epsilon$ , even though the calculations become increasingly complex as the order increases.

Finally, let us state a slight generalization of (124), which we use below. In the integral (123), we replace  $f(u)$  by  $f(u) + \epsilon g(u)$ . Then, as  $\epsilon \rightarrow 0$ ,

$$\int_0^\infty [f(u) + \epsilon g(u)] e^{-\phi(u)/\epsilon} du = \sqrt{\frac{2\pi\epsilon}{\phi''(u_0)}} e^{-\phi(u_0)/\epsilon} \times \left\{ f(u_0) + \epsilon \left[ g(u_0) + \frac{f''(u_0)}{2\phi''(u_0)} - \frac{\phi^{(4)}(u_0) f(u_0)}{8\phi''(u_0)^2} - \frac{f'(u_0) \phi^{(3)}(u_0)}{2\phi''(u_0)^2} + \frac{5\phi^{(3)}(u_0)^2 f(u_0)}{24\phi''(u_0)^3} \right] + O(\epsilon^2) \right\}. \quad (125)$$

This formula follows immediately from (124).

### B.3 Application of Laplace's method

We shall now apply formula (125) to evaluate the integrals (84) and (91). Each of these integrals is of the form given by the right hand side of (125). We find easily that the minimum  $Y_0$  of the function

$$\phi(Y) = \frac{1}{2} \delta(z, Z)^2$$

is given by

$$Y_0 = y \sqrt{\zeta^2 - 2\rho\zeta + 1},$$

where

$$\zeta = \frac{1}{y} \int_X^x \frac{du}{C(u)}.$$

Also, we let  $D(\zeta)$  denote the value of  $\delta(z, Z)$  with  $Y = Y_0$ :

$$D(\zeta) = \log \frac{\sqrt{\zeta^2 - 2\rho\zeta + 1} + \zeta - \rho}{1 - \rho},$$

and

$$I(\zeta) = \sqrt{\zeta^2 - 2\rho\zeta + 1}.$$

Finally, we note that the second derivative  $\phi''(Y_0)$  of  $\phi(Y)$  with respect to  $Y$  is

$$\phi''(Y_0) = \frac{D}{(1 - \rho^2) y^2 I \sinh D},$$

where we have suppressed the argument  $\zeta$  in  $D(\zeta)$  and  $I(\zeta)$ . Likewise,

$$\phi^{(3)}(Y_0) = -\frac{3D}{(1 - \rho^2) y^3 I^2 \sinh D},$$

and

$$\phi^{(4)}(Y_0) = \frac{3(1 - D \coth D)}{(1 - \rho^2)^2 y^4 I^2 \sinh^2 D} + \frac{12D}{(1 - \rho^2) y^4 I^3 \sinh D}.$$

It is actually easier to begin the calculation with (91). In order to evaluate the various terms on the right hand side of (125), let us define

$$f(Y) = \sqrt{\frac{\delta}{\sinh \delta}} \left( 1 - \frac{\delta}{\sinh \delta} q \right),$$

and

$$g(Y) = -\sqrt{\frac{\delta}{\sinh \delta}} \left( \frac{1}{8} + \frac{\delta \coth \delta - 1}{8\delta^2} - \frac{3(1 - \delta \coth \delta) + \delta^2}{8\delta \sinh \delta} q \right).$$

Then, after some manipulations we find that:

$$f(Y_0) = \sqrt{\frac{D}{\sinh D}} \left( 1 + \frac{yC'(x)D}{2\sqrt{1 - \rho^2}I} \right),$$

$$f'(Y_0) = -\left( \frac{D}{\sinh D} \right)^{3/2} \frac{C'(x)(\sinh(D) - \rho \cosh(D))}{2(1 - \rho^2)^{3/2} I^2},$$

$$\begin{aligned} f''(Y_0) &= \sqrt{\frac{D}{\sinh D}} \frac{1 - D \coth D}{2(1 - \rho^2) y^2 I D \sinh D} \left( 1 + \frac{3yC'(x)D}{2\sqrt{1 - \rho^2}I} \right) \\ &+ \left( \frac{D}{\sinh D} \right)^{3/2} \frac{C'(x)(\sinh(D) - \rho \cosh(D))}{(1 - \rho^2)^{3/2} y I^3}, \end{aligned}$$

and

$$g(Y_0) = -\frac{1}{8} \sqrt{\frac{D}{\sinh D}} \left[ 1 - \frac{1 - D \coth D}{D^2} + yC'(x) \frac{3(1 - D \coth D) + D^2}{2\sqrt{1 - \rho^2} I D} \right].$$

Putting all these together we find that

$$M_X^2(s, x, y) = \frac{1}{\sqrt{2\pi\lambda}} yC(X) \sqrt{I} \exp\left\{-\frac{D^2}{2\lambda}\right\} \left\{1 + \frac{yC'(x)D}{2\sqrt{1-\rho^2}I}\right. \\ \left. + \frac{1}{8}\lambda \left[1 - \frac{yC'(x)D}{2\sqrt{1-\rho^2}I} + \frac{2\rho yC'(x)}{\sqrt{1-\rho^2}I^2} \cosh(D)\right. \right. \\ \left. \left. + \left(\frac{3(1-\rho^2)}{I} + \frac{2yC'(x)(3\rho^2-4)D}{\sqrt{1-\rho^2}I^2}\right) \frac{\sinh(D)}{D}\right] + O(\lambda^2)\right\},$$

as claimed in Section 5.

Let us now compute (84). We note that the functions  $f$  and  $g$  in (125) occurring in this integral are obtained from the corresponding functions in (84) by dividing them by  $Y^2$ . We thus define

$$\tilde{f}(Y) = \frac{f(Y)}{Y^2},$$

and

$$\tilde{g}(Y) = \frac{g(Y)}{Y^2}.$$

Then,

$$\tilde{f}(Y_0) = \frac{f(Y_0)}{y^2 I^2}, \\ \tilde{f}'(Y_0) = -\frac{2f(Y_0)}{y^3 I^3} + \frac{f'(Y_0)}{y^2 I^2}, \\ \tilde{f}''(Y) = \frac{6f(Y_0)}{y^4 I^4} - \frac{4f'(Y_0)}{y^3 I^3} + \frac{f''(Y_0)}{y^2 I^2},$$

and

$$\tilde{g}(Y_0) = \frac{g(Y_0)}{y^2 I^2}.$$

Combining all the terms we find that

$$P_X(s, x, y) = \frac{1}{\sqrt{2\pi\lambda}} \frac{1}{yC(X) I^{3/2}} \exp\left\{-\frac{D^2}{2\lambda}\right\} \left\{1 + \frac{yC'(x)D}{2\sqrt{1-\rho^2}I}\right. \\ \left. - \frac{1}{8}\lambda \left[1 + \frac{yC'(x)D}{2\sqrt{1-\rho^2}I} + \frac{6\rho yC'(x)}{\sqrt{1-\rho^2}I^2} \cosh(D)\right. \right. \\ \left. \left. - \left(\frac{3(1-\rho^2)}{I} + \frac{3yC'(x)(5-\rho^2)D}{2\sqrt{1-\rho^2}I^2}\right) \frac{\sinh(D)}{D}\right] + O(\lambda^2)\right\},$$

as stated in Section 5.

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